

MATHEMATICAL MODEL CHECKING FOR COMPUTER SCIENCE EDUCATION



Wolfgang Schreiner

Research Institute for Symbolic Computation (RISC)

Johannes Kepler University Linz, Austria



Formal Modeling&Reasoning in Education

Definition 1.34 (Satisfaction). Satisfaction of a formula φ in a structure \mathfrak{M} relative to a variable assignment s , in symbols: $\mathfrak{M}, s \models \varphi$, is defined recursively as follows. (We write $\mathfrak{M}, s \not\models \varphi$ to mean “not $\mathfrak{M}, s \models \varphi$.”)

1. $\varphi \equiv \perp$: $\mathfrak{M}, s \not\models \varphi$.
2. $\varphi \equiv \top$: $\mathfrak{M}, s \models \varphi$.
3. $\varphi \equiv R(t_1, \dots, t_n)$: $\mathfrak{M}, s \models \varphi$ iff $(\text{Val}_s^{\mathfrak{M}}(t_1), \dots, \text{Val}_s^{\mathfrak{M}}(t_n)) \in R$.
4. $\varphi \equiv t_1 = t_2$: $\mathfrak{M}, s \models \varphi$ iff $\text{Val}_s^{\mathfrak{M}}(t_1) = \text{Val}_s^{\mathfrak{M}}(t_2)$.
5. $\varphi \equiv \neg\psi$: $\mathfrak{M}, s \models \varphi$ iff $\mathfrak{M}, s \not\models \psi$.
6. $\varphi \equiv (\psi \wedge \chi)$: $\mathfrak{M}, s \models \varphi$ iff $\mathfrak{M}, s \models \psi$ and $\mathfrak{M}, s \models \chi$.
7. $\varphi \equiv (\psi \vee \chi)$: $\mathfrak{M}, s \models \varphi$ iff $\mathfrak{M}, s \models \psi$ or $\mathfrak{M}, s \models \chi$.
8. $\varphi \equiv (\psi \rightarrow \chi)$: $\mathfrak{M}, s \models \varphi$ iff $\mathfrak{M}, s \not\models \psi$ or $\mathfrak{M}, s \models \chi$.
9. $\varphi \equiv (\psi \leftrightarrow \chi)$: $\mathfrak{M}, s \models \varphi$ iff either $\mathfrak{M}, s \models \psi$ and $\mathfrak{M}, s \models \chi$ or neither $\mathfrak{M}, s \models \psi$ nor $\mathfrak{M}, s \models \chi$.
10. $\varphi \equiv \forall x \psi$: $\mathfrak{M}, s \models \varphi$ iff for every x -valued s' , $\mathfrak{M}, s' \models \psi$.
11. $\varphi \equiv \exists x \psi$: $\mathfrak{M}, s \models \varphi$ iff there is an x -valued s' such that $\mathfrak{M}, s' \models \psi$.

$\frac{\Gamma, B \vdash \Delta}{\Gamma, A \wedge B \vdash \Delta} (\wedge L_2)$	$\frac{\Gamma \vdash B, \Delta}{\Gamma \vdash A \vee B, \Delta} (\vee R_2)$
$\frac{\Gamma, A \vdash \Delta \quad \Sigma, B \vdash \Pi}{\Gamma, \Sigma, A \vee B \vdash \Delta, \Pi} (\vee L)$	$\frac{\Gamma \vdash A, \Delta}{\Gamma, \Sigma \vdash \Delta} (\wedge R)$
$\frac{\Gamma \vdash A, \Delta \quad \Sigma, B \vdash \Pi}{\Gamma, \Sigma, A \rightarrow B \vdash \Delta, \Pi} (\rightarrow L)$	$\frac{\Gamma, A \vdash \Delta}{\Gamma \vdash \Delta} (\rightarrow R)$
$\frac{\Gamma \vdash A, \Delta}{\Gamma, \neg A \vdash \Delta} (\neg L)$	$\frac{\Gamma \vdash \Delta}{\Gamma \vdash \Delta} (\neg R)$
$\frac{\Gamma, A[t/x] \vdash \Delta}{\Gamma, \forall x A \vdash \Delta} (\forall L)$	$\frac{\Gamma \vdash \Delta}{\Gamma \vdash \Delta} (\forall R)$
$\frac{\Gamma, A[y/x] \vdash \Delta}{\Gamma, \exists x A \vdash \Delta} (\exists L)$	$\frac{\Gamma \vdash \Delta}{\Gamma \vdash \Delta} (\exists R)$

$\mathcal{A} : \mathbf{Aexp} \rightarrow (\Sigma \rightarrow \mathbf{N})$

$\mathcal{B} : \mathbf{Bexp} \rightarrow (\Sigma \rightarrow \mathbf{T})$

$\mathcal{C} : \mathbf{Com} \rightarrow (\Sigma \rightarrow \Sigma)$

$\mathcal{C}[\text{skip}] = \{(\sigma, \sigma) \mid \sigma \in \Sigma\}$

$\mathcal{C}[X := a] = \{(\sigma, \sigma[n/X]) \mid \sigma \in \Sigma \text{ \& } n = \mathcal{A}[a]\sigma\}$

$\mathcal{C}[c_0; c_1] = \mathcal{C}[c_1] \circ \mathcal{C}[c_0]$

$\mathcal{C}[\text{if } b \text{ then } c_0 \text{ else } c_1] =$
 $\{(\sigma, \sigma') \mid \mathcal{B}[b]\sigma = \text{true} \text{ \& } (\sigma, \sigma') \in \mathcal{C}[c_0]\} \cup$
 $\{(\sigma, \sigma') \mid \mathcal{B}[b]\sigma = \text{false} \text{ \& } (\sigma, \sigma') \in \mathcal{C}[c_1]\}$

$\mathcal{C}[\text{while } b \text{ do } c] = \text{fix}(\Gamma)$

$\Gamma(\varphi) = \{(\sigma, \sigma') \mid \mathcal{B}[b]\sigma = \text{true} \text{ \& } (\sigma, \sigma') \in \varphi \circ \mathcal{C}[c]\} \cup$
 $\{(\sigma, \sigma) \mid \mathcal{B}[b]\sigma = \text{false}\}.$

Typically still presented as “paper and pencil” topics.

Formal Modeling&Reasoning in Education

RISC Algorithm Language (RISCAL)

File Edit Help

File: /software/RISCAL/spec/gcd.txt

```
1// -----
2// Computing the greatest common divisor by the Euclidean Algorithm
3// -----
4
5val N: N;
6type nat = N[N];
7
8pred divides(m:nat,n:nat) =  $\exists p$ . nat. m = p * n;
9
10fun gcd(m:nat,n:nat): nat
11  requires m ≠ 0 ∧ n ≠ 0;
12  = choose result:nat with
13    divides(result,m) ∧ divides(result,n) ∧
14    ¬∑r.nat. divides(r,m) ∧ divides(r,n) ∧ r > result;
15
16theorem gcd(m:nat) = m = 0 ⇒ gcd(m,0) = m;
17theorem gcd(m:nat,n:nat) = m ≠ 0 ∧ n ≠ 0 ⇒ gcd(a,m) = gcd(n,m);
18theorem gcd(m:nat,n:nat) = 1 ≤ n ∧ m ≤ n ⇒ gcd(m,n) = gcd(m,n);
19
20proc gcd(m:nat,n:nat): nat
21  requires m ≠ 0 ∧ n ≠ 0;
22  ensures result = gcd(m,n);
23 {
24   var a:nat = m;
25   var b:nat = n;
26   while a > 0 ∧ b > 0 do
27     invariant a = 0 ∨ b = 0;
28     invariant gcd(a,b) = gcd(oid a,oid b);
29     decreases a+b;
30   {
31     if a > b then
32       a = a-b;
33     else
34       b = b-a;
35   }
36   return if a = 0 then b else a;
37 }
38
39fun gcdf(m:nat,n:nat): nat
40  invariant m ≠ 0 ∧ n ≠ 0;
```

Exercise: Formal Specification

JKU LIT Project LogTechEdu

Submitter: Wolfgang Schreiner

1 of 2 grade points have been earned so far.

Unlock Exercise Reset Exercise Get Certificate

TASK DESCRIPTION:

In the following we consider arrays of maximum length N whose elements are natural numbers of maximum size M:

```
val N = 4; // choose small values
val M = 3;
type Elem = N[M]; type Arr = Array[N,Elem]; type Index = Z[-1,
```

Take the problem of finding the smallest index i at which an element e occurs among the first n elements of an array a. Your task is to develop a formal specification of this problem, i.e., to define a predicate P(a,n,e), the input condition of the problem, and a predicate Q(a,n,e,i), the output condition.

```
pred P(a:Arr,n:Index,e:Elem) =
  // formulate here the input condition
  0 ≤ n ∧
  ∃ i:Index. 0 ≤ i ∧ i < n ∧ a[i] = e

pred Q(a:Arr,n:Index,e:Elem,i:Index) =
  // formulate here the output condition
  0 ≤ i ∧ i < n ∧ a[i] = e ∧
  ∀ i0:Index. 0 ≤ i0 ∧ i0 < n ∧ a[i0] = e ⇒ i ≤ i0
```

TASK: check whether your specification adequately specifies the following code

Check correctness


Execution completed for ALL inputs (268 n SUCCESS termination.

16:54 74%

AXoloti

Problem and Rules

$((p \Rightarrow q) \vdash ((q \Rightarrow r) \Rightarrow (p \Rightarrow r)))$



$\Delta, (w \vdash (x \Rightarrow y), z) \Rightarrow \Delta, (x, w \vdash y)$

$\Delta, ((x \Rightarrow y), z \vdash w) \Rightarrow \Delta, (z \vdash x, w)$

$\Delta, (w \vdash x, y, z) \Rightarrow \Delta, (w \vdash y, z, x)$

$\Delta, (x, y, z \vdash w) \Rightarrow \Delta, (y, z, x \vdash w)$

$\Delta \vdash (x \vdash x) \Rightarrow \Delta$

III <

But today the educational process can be substantially supported by software.

Projects LOGTECHEDU and SemTech

- **LOGTECHEDU:** Logic Technologies for Computer Science Education.
 - JKU LIT (Linz Institute of Technology), 2018–2020.
 - Institutes FMV (Biere, Cerna, Seidl) and RISC (Schreiner, Windsteiger).
 - <http://fmv.jku.at/logtechedu>
- **SemTech:** Semantic Technologies for Computer Science Education.
 - Austrian OEAD WTZ and Slovak SRDA, 2018–2019.
 - JKU Linz (Schreiner) and TU Kosice (Novitzká, Steingartner).
 - <https://www.risc.jku.at/projects/SemTech>

Investigate the potential of formal modeling&reasoning software for education.

Educating with the Help of Formal Models

- Today much of modeling&reasoning can be **automated by computer software**.
 - Substantial advances in computational logic (automated reasoning, model checking, satisfiability solving).
- By the application of such software **education may be supported**.
 - May demonstrate the practical usefulness of theory.
 - May increase the motivation of students to model and to reason.
- The ultimate goal is **self-directed learning**.
 - Teachers become “enablers” by providing basic knowledge and skills.
 - Students “educate themselves” by solving problems.
 - (Voluntary) quizzes, (mandatory) assignments, possibly (graded) exams.

Core idea: let students actively engage with lecturing material by solving concrete problems and by receiving immediate feedback from the software.

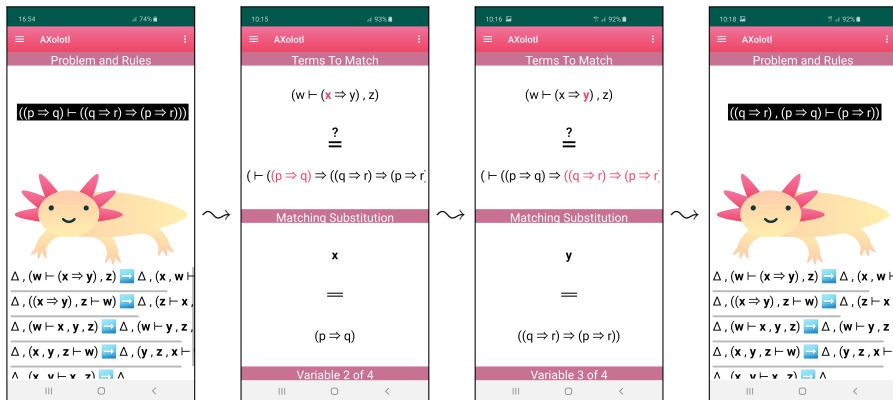
Research Strands

- Solver Guided Exercises (Limboole, Boolector)
- Teaching Solver Technology (Limboole, Boolector)
- Proof Assistants for Education (Theorema, AXolotl)
- Specification and Verification Systems for Education (RISCAL)
- Formal Semantics of Programming Languages (*Jane*)
- Logic across the Subjects in Primary, Secondary and Higher Education

Various aspects of the general idea.

Example: AXolotl

Author: David Cerna; Google Play Store (search for “AXolotl Logic Software”)



Proving on a smartphone by a purely touch-based interface (no keyboard input).

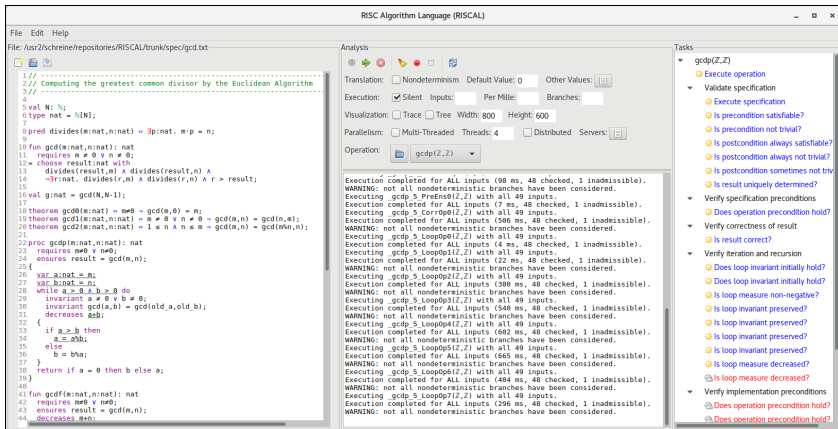
The RISC Algorithm Language (RISCAL)

A language and software system for investigating finite mathematical models (i.e., a “mathematical model checker”).

- Formulation of mathematical theories and theorems.
- Formulation and specification of (also non-deterministic) algorithms.
- Rooted in strongly typed first order logic and set theory.
- All types are finite (with sizes determined by model parameters).
- All formulas are automatically decidable.
- Correctness of all algorithms is decidable.
- Automatic generation of (again decidable) verification conditions.

Checking in some model of fixed size *before* proving in models of arbitrary size.

The RISCAL Software



<https://www.risc.jku.at/research/formal/software/RISCAL>

Theories and Theorems

```
val N:  $\mathbb{N}$ ;
type Literal =  $\mathbb{Z}[-N,N]$ ;
type Clause = Set[Literal] with  $\neg \exists l \in \text{value}. \neg l \in \text{value}$ ;
type Formula = Set[Clause];
type Valuation = Set[Literal];

pred satisfies(v:Valuation, l:Literal)  $\Leftrightarrow l \in v$ ;
pred satisfies(v:Valuation, c:Clause)  $\Leftrightarrow \exists l \in c. \text{satisfies}(v, l)$ ;
pred satisfies(v:Valuation, f:Formula)  $\Leftrightarrow \forall c \in f. \text{satisfies}(v, c)$ ;
pred satisfiable(f:Formula)  $\Leftrightarrow \exists v: \text{Valuation}. \text{satisfies}(v, f)$ ;
pred valid(f:Formula)  $\Leftrightarrow \forall v: \text{Valuation}. \text{satisfies}(v, f)$ ;
fun not(f: Formula):Formula = { c | c:Clause with  $\forall d \in f. \exists l \in d. \neg l \in c$  };

theorem notValid(f:Formula)  $\Leftrightarrow \text{valid}(f) \Leftrightarrow \neg \text{satisfiable}(\text{not}(f))$ ;
```

First-order logic, integers, tuples/records, arrays/maps, sets, algebraic types.

Declarative Algorithms

```
fun literals(f:Formula):Set[Literal] = {l | l:Literal with  $\exists c \in f. l \in c$ };  
  
fun substitute(f:Formula,l:Literal):Formula = {c\{-l} | c  $\in f$  with  $\neg(l \in c)$ };  
  
multiple pred DPLL(f:Formula)  
  ensures result  $\Leftrightarrow$  satisfiable(f);  
  decreases |literals(f)|;  
 $\Leftrightarrow$   
  if f =  $\emptyset$ [Clause] then  
    T  
  else if  $\emptyset$ [Literal]  $\in$  f then  
     $\perp$   
  else  
    choose l  $\in$  literals(f) in  
      DPLL(substitute(f,l))  $\vee$  DPLL(substitute(f,-l));
```

Functions, predicates, implicitly defined constants and functions.

Imperative Algorithms

```
proc DPLL2(f:Formula): Bool
  ensures result  $\Leftrightarrow$  satisfiable(f);
{
  var satisfiable: Bool =  $\perp$ ;
  var stack: Array[N+1,Formula] = Array[N+1,Formula]( $\emptyset$ [Clause]);
  var number:  $\mathbb{N}$ [N+1] = 0;
  stack[number] = f; number = number+1;
  while  $\neg$ satisfiable  $\wedge$  number>0 do
    invariant  $0 \leq \text{number} \wedge \text{number} \leq N+1$ ;
    invariant number > 0  $\wedge$  stack[number-1]  $\neq \emptyset$ [Clause]  $\wedge \neg \emptyset$ [Literal]  $\in$  stack[number-1]  $\Rightarrow$  number < N+1;
    invariant satisfiable(f)  $\Leftrightarrow$  satisfiable  $\vee \exists i:\mathbb{N}[N+1]$  with  $i < \text{number}$ . satisfiable(stack[i]);
    decreases if satisfiable then 0 else  $\sum k:\mathbb{N}[N]$  with  $k < \text{number}$ . size(stack[k]);
  {
    number = number-1;
    var g:Formula = stack[number];
    if g =  $\emptyset$ [Clause] then
      satisfiable =  $\top$ ;
    else if  $\neg \emptyset$ [Literal]  $\in$  g then
      {
        choose l  $\in$  literals(g);
        stack[number] = substitute(g, -l); number = number+1;
        stack[number] = substitute(g, l); number = number+1;
      }
    }
  }
  return satisfiable;
}
```

Procedures, variables, loops.

Transition Systems

```
proc system(x0: Positions, y0: Positions): ()
  requires init(x0, y0);
{
  var x: Positions = x0; var y: Positions = y0;

  var rs: Array[N+1,Robot] = Array[N+1,Robot](0);
  var ds: Array[N+1,Direction] = Array[N+1,Direction](Direction!Stop);

  for var i:N[N] = 0; i < N; i = i+1 do
  {
    choose r: Robot, d: Direction with nextDir(x, y, r, d);
    rs[i] := r; ds[i] = d;

    x = moveX(x, r, d); y = moveY(y, r, d);
    assert noCollision(x, y) v print rs, ds in 1;
  }
}
```

Nondeterministic systems defined by initial state condition and next state relation.

RISCAL Checking

Using N=2.

Type checking and translation completed.

...

Executing `notValid(Set[Set[\mathbb{Z}]])` with selected 512 inputs.

Execution completed for SELECTED inputs (111 ms, 512 checked, 0 inadmissible).

Executing `DPLL(Set[Set[\mathbb{Z}]])` with selected 512 inputs.

Execution completed for SELECTED inputs (1219 ms, 512 checked, 0 inadmissible).

Executing `DPLL2(Set[Set[\mathbb{Z}]])` with selected 512 inputs.

435 inputs (435 checked, 0 inadmissible, 0 ignored)...

Execution completed for SELECTED inputs (2436 ms, 512 checked, 0 inadmissible).

Executing `DPLL_OutputCorrect(Set[Set[\mathbb{Z}]])` with selected 512 inputs.

Execution completed for SELECTED inputs (609 ms, 512 checked, 0 inadmissible).

Automatic checking of theorems, algorithms, generated verification conditions.

Application: Mathematical Modeling

```
val N:N; // variable x0,...,xN
val M:N; // values 0,...,M

type Var = N[N];           // a variable
type Val = N[M];           // a value
type Ass = Map[Var,Val];    // an assignment of variables to values
type Pred = Set[Ass];       // a predicate as a set of assignments

val Ass = { a | a:Ass };

pred independent(P:Pred, x:Var) ⇔
  ∀a:Ass, v1:Val, v2:Val.
    (a with [x] = v1) ∈ P ⇔ (a with [x] = v2) ∈ P;

fun EXISTS(x:Var, P:Pred):Pred =
  { a | a:Ass with ∃v:Val. (a with [x] = v) ∈ P } ;
theorem Exists1(x:Var, P:Pred) ⇔
  ∀Q:Pred with independent(Q,x). Q = EXISTS(x,P) ⇔
    P ⊆ Q ∧ ∀Q0:Pred with independent(Q0,x). P ⊆ Q0 ⇒ Q ⊆ Q0;
theorem Exists2(x:Var, P:Pred) ⇔
  EXISTS(x,P) = ⋂{ Q | Q:Pred with independent(Q,x) ∧ P ⊆ Q };
```

Executing Exists1(\mathbb{Z} , Set[Array[\mathbb{Z}]]) with all 768 inputs.

Execution completed for ALL inputs (4311 ms, 768 checked, 0 inadmissible).

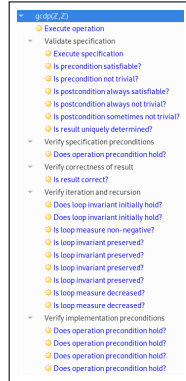
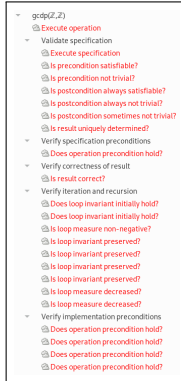
Executing Exists2(\mathbb{Z} , Set[Array[\mathbb{Z}]]) with all 768 inputs.

Execution completed for ALL inputs (1674 ms, 768 checked, 0 inadmissible).

Validating conjectures (respectively the formalization of theorems).

Application: Specifying and Verifying Algorithms

```
proc gcdp(m:nat,n:nat): nat
  requires m≠0 ∨ n≠0;
  ensures result = gcd(m,n);
{
  var a:nat = m;
  var b:nat = n;
  while a > 0 ∧ b > 0 do
    invariant a ≠ 0 ∨ b ≠ 0;
    invariant gcd(a,b) = gcd(old_a,old_b);
    decreases a+b;
  {
    if a > b then
      a = a%b;
    else
      b = b%a;
  }
  return if a = 0 then b else a;
}
```



Executing `gcdp(Z,Z)` with all 121 inputs.

Execution completed for ALL inputs (172 ms, 120 checked, 1 inadmissible).

...

Executing `_gcdp_5_PreOp3(Z,Z)` with all 121 inputs.

87 inputs (86 checked, 1 inadmissible, 0 ignored)...

Execution completed for ALL inputs (2843 ms, 120 checked, 1 inadmissible).

Validating algorithms, their specification, annotations, verification conditions. 15/23

RISCAL Approach to Model Checking/Formula Decision

$ComSem := Single + Multiple$

$Single := Command \rightarrow (Context \rightarrow Context)$

$Multiple := Command \rightarrow (Context \rightarrow Seq(Context))$

$Seq(T) := Unit \rightarrow (Null + Next(T, Seq(T)))$

$\llbracket . \rrbracket : Command \rightarrow Single$

$\llbracket \text{if } E \text{ then } C \rrbracket := \lambda c. \text{if } \llbracket E \rrbracket(c) \text{ then } \llbracket C \rrbracket(c) \text{ else } c$

```
interface ComSem {  
    public interface Single extends ComSem, Function<Context,Context> { }  
    public interface Multiple extends ComSem, Function<Context,Seq<Context> > { }  
}  
interface Seq<T> extends Supplier<Seq.Next<T> > { ... }  
  
ComSem.Single ifThenElse(BoolExpSem.Single E, ComSem.Single C)  
{ return (Context c) -> E.apply(c) ? C.apply(c) : c; }
```

Translation of every RISCAL phrase to its (potentially nondeterministic) semantics
and the execution of this semantics.

RISCAL Formula Decision (Experimental Alternative)

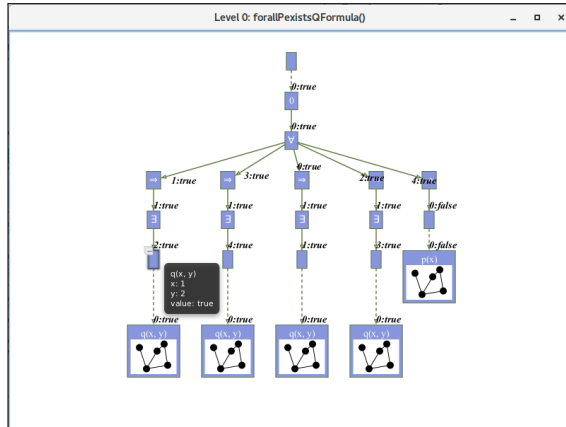
```
(set-logic QF_UFBV)
(declare-fun x() (_ BitVec 4))
(define-fun y() (_ BitVec 4)#b0001)
(assert (not (bvule x (bvadd x y))))
(check-sat)
(exit)
```

■ Translation of RISCAL theory to SMT-LIB.

- Author: Franz-Xaver Reichl (master thesis).
- QF_UFBV: quantifier-free formulas over bitvectors with uninterpreted functions.
- Well supported by various SMT solvers: Boolector, Z3, Yices, CVC4, ...
- Elimination of quantifiers by skolemization and expansion.
- Translation of integers, tuples/records, arrays/maps, sets, ... to bit vectors.
 - Non-trivial because, e.g., RISCAL uses “true” mathematical integers.

Much faster in many (not all) cases, systematic benchmarks under way.

RISCAL Visualization



Pruned evaluation trees to explain the truth value of a formula.

RISCAL Counterexample Generation

```
theorem _search_0_LoopOp6(a:array, x:elem)  $\Leftrightarrow$   
   $\forall i:\text{int}, r:\text{int}. (((((0 \leq i) \wedge (i \leq N)) \wedge \dots) \Rightarrow$   
    (let i = i+1 in  
      ( $\forall j:\text{int}. (((0 \leq j) \wedge (j < i)) \Rightarrow (a[j] \neq x))))))$ );
```

ERROR in execution of _search_0_LoopOp6([0,0],0): evaluation of
 _search_0_LoopOp6
at unknown position:
 theorem is not true
ERROR encountered in execution.

Executing __search_0_LoopOp6_refute().

This sequence of assignments leads to a counterexample
(note the underlined editor lines):

a=[0,0],x=0

i=0,r=-1

i=1

j=0

```
var i:int = 0;  
var r:int = -1;  
while i < N  $\wedge$  r = -1 do  
  invariant 0  $\leq$  i  $\wedge$  i  $\leq$  N;  
  invariant  $\forall j:\text{int}. 0 \leq j \wedge j < i \Rightarrow a[j] \neq x$ ;  
  invariant r = -1  $\vee$  (r = i  $\wedge$  i < N  $\wedge$  a[r] = x);  
  decreases if r = -1 then N-i else 0;  
  {  
    if a[i] = x then r = i;  
    i = i+1;  
  }  
return r;
```

Core information to explain the invalidity of a formula.

RISCAL Web Exercises

Exercise: Formal Specification

JKU LIT Project LogTechEdu

Submitter: Wolfgang Schreiner

1 of 2 grade points have been earned so far.

Unlock Exercise

Reset Exercise

Get Certificate

TASK DESCRIPTION:

In the following we consider arrays of maximum length N whose elements are natural numbers of maximum size M :

```
val N = 4 ; // choose small values
val M = 3 ;
type Elem = N[M]; type Arr = Array[N,Elem]; type Index = Z[-1,N];
```

Take the problem of finding the smallest index i at which an element e occurs among the first n elements of an array a . Your task is to develop a formal specification of this problem, i.e., to define a predicate $P(a,n,e)$, the input condition of the problem, and a predicate $Q(a,n,e,i)$, the output condition.

```
pred P(a:Arr,n:Index,e:Elem) =
  // formulate here the input condition
  0 ≤ n ∧
  ∃i:Index. 0 ≤ i ∧ i < n ∧ a[i] = e

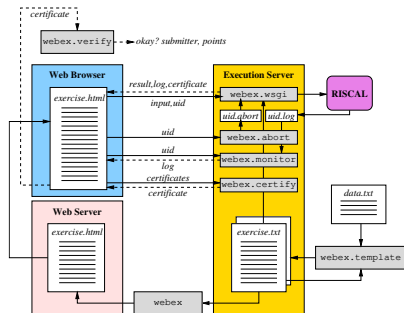
pred Q(a:Arr,n:Index,e:Elem,i:Index) =
  // formulate here the output condition
  0 ≤ i ∧ i < n ∧ a[i] = e ∧
  ∀i0:Index. 0 ≤ i0 ∧ i0 < n ∧ a[i0] = e → i ≤ i0
```

TASK: check whether your specification adequately specifies the following code ...

Check correct()



Execution completed for ALL inputs (268 ms, 1296 checked, 2800 inadmissible).
SUCCESS termination.



Framework for web-based exercises checked by a RISCAL server.

Educational Usage

- **“Formal Methods in Software Development”** (JKU, master programs “Computer Science” and “Computer Mathematics”)
 - RISCAL: formal problem specifications; specification and verification of imperative programs.
- **“Formal Methods and Specification”** (TU Prague, Stefan Ratschan, master program “Informatics”)
 - RISCAL: formal specification and verification of imperative programs.
- **“Formal Modeling”** (JKU, bachelor program “Technical Mathematics”)
 - RISCAL: formal modeling of computational problems, search and scheduling problems (“puzzles”), dynamic systems.
- **“Logic”** (JKU, bachelor prog. “Computer Science” and “Artificial Intelligence”)
 - RISCAL, AXolotol, Theorema, Limboole, Boolector, Z3.
 - Bonus (RISCAL Web) and laboratory exercises (RISCAL desktop, AXolotol).
- **Various Bachelor and Master Theses**

RISCAL Experience

Observations, results of questionnaires, test/exam results.

- Students with some technical/formal background (2nd year and higher):
 - ☐ High satisfaction with ease of use.
 - ☐ Much more liked than “proof-based” logic software.
 - ☐ Many students were indeed enabled to independently develop adequate formal specifications, models, program annotations.
- Absolute beginners (1st semester):
 - ☐ More used than other tools on FO and SMT (but less than SAT solvers).
 - ☐ Those who performed the exercises scored better in tests.
 - ☐ Students that scored poorly in tests did not use the software.
 - ☐ “Extrinsic motivation”: mainly used to get additional grade points.

From a certain background/level on, substantial increase in motivation and interest (but not a statistically significant effect on grades).

Conclusions and Further Work

- Formal modeling&reasoning software can indeed be a factor to increase interest in “formal” topics and foster “self-directed” learning.
- However, students mainly profit if they already have certain abilities respectively some background.
- Care has to be taken to not “loose” the weaker beginners; these are easily overwhelmed by information overload or (trivial) syntactic/technical difficulties.
- We are currently running a beginner’s course with an easier to use web-based interface and will evaluate the difference it makes.
- Future work will concentrate on development of software-based course materials and on technical extensions (integration with interactive provers, modeling and reasoning about concurrency).

<https://www.risc.jku.at/research/formal/software/RISCAL>